

**Amendments To The Claims:**

**Claim 1**      *(Currently Amended)*      A fork-lift truck having comprising:  
a mast,  
a load carrying fork,  
a pair of actuation drives, one being a lifting and lowering drive, and one being an  
inclination drive,  
an analog sensor, and  
a control device, wherein:  
a the load-carrying ~~means having a load-carrying fork~~ which is engaged to and  
supported by the mast and is adjustable in height by ~~means of a~~ the lifting and lowering drive,  
wherein the inclined position of the load-carrying fork is adjustable ~~with respect~~  
relative to the ~~a horizontal line axis by means of an inclination~~ the inclination drive, and  
and an the ~~electric~~ control ~~and regulation~~ device is in electrical communication with  
and regulates the actuation of the lifting and lowering drive and is in separate electrical  
communication with and separately regulates the inclination drive, for the respective drives which is  
connected to operating members for the lifting and lowering drive and inclination drive, characterized  
in that an  
said regulation comprises utilizing the analog sensor (40) to detect ~~detecting~~ the  
inclined position of the load-carrying fork (28) ~~is provided the~~ and correspondingly emitting an  
inclination signal of which is sent to the control device, and regulation device (42) and that the control  
and regulation device (42) is connected to a separate operating member (54) for the inclination drive  
~~or the operating member (52) for the inclination drive~~ the control device in turn processes the  
inclination signal and induces is configured in such a way that a coordinated actuation of at least one

~~of the actuation drives such that they actuating it causes cause~~ the load-carrying fork (28) to be automatically moved to a predetermined position, ~~preferably a horizontal position.~~

**Claim 2** (Currently Amended) The fork-lift truck ~~of~~ as ~~claimed in~~ claim 1, characterized in that the control device ~~inclination sensor (40)~~ measures the inclined position of the load-carrying fork (28) relative to the horizontal line induces the load-carrying fork to be automatically moved to a horizontal position.

**Claim 3** (Currently Amended) The fork-lift truck as claimed in claim 1, characterized in that the control device induces control and regulation device (42) sends a signal to the inclination drive to move ~~it~~ the load-carrying fork colinear with ~~to~~ the horizontal line axis when a signal the lifting and lowering drive are induced by the control device to be actuated ~~for lowering or lifting the load-carrying means (28) is produced by the operating member (46) for the lifting and lowering operation.~~

**Claim 4** (Currently Amended) The fork-lift truck as claimed in claim 1 further comprising an engine and an onboard computer, the engine controlling the speed of the fork-lift truck, characterized in that the control and regulation device (42) is connected to an onboard computer (56) ~~or forms part thereof,~~ the onboard computer in controlling communication with the engine such that it (56) limits the traveling speed and/or cornering speed of the fork-lift truck in conformity with stability criteria, and the inclination signal of the ~~inclination sensor (40)~~ is also sent to ~~received by~~ the onboard computer (56) for a modification of the maximum traveling speed of the fork-lift truck in dependence on the inclination signal ~~of the inclination sensor (40).~~

**Claim 5**      *(New)*      The fork-lift truck of claim 1, characterized in that the control device measures the inclined position of the load-carrying fork relative to the horizontal axis.

**Claim 6**      *(New)*      The fork-lift truck of claim 1, characterized in that the control device induces the load-carrying fork to be automatically moved to a pre-determined height.